151 XD 2103

# **XD** series

Proportional, industrial hand grip controllers • non-contacting Hall effect technology



#### **DISTINCTIVE FEATURES**

SIL 2 compatible - Redundant Hall sensors Resists high axial load (1780 N - 400 lbf) Shallow mounting depth of <60 mm (2.36) Rated for 10 million lifecycles SAE CAN bus J1939-71



#### **ENVIRONMENTAL SPECIFICATIONS**

- Operating Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
- Storage Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
- Above Panel Sealing: Up to IP67 (subject to handle configuration)
- Humidity: IEC 60068-2-38
- Thermal shock: SAE J1455 section 4.1.3.2
- Salt spray: IEC 60068-2-11
- Random vibration: IEC 60068-2-64
- Sinusoidal vibration: IEC 60068-2-6
- EMC Emissions:
- Radiated Emissions Level: ECE/324/Add.9:2012; CISPR 25:2002
- Radiated Emissions Level: CISPR 25:2008
- EMC Immunity:
- ESD: ISC 10605:2008; criteria A
- Radiated immunity: ISO 11452-2:2004; criteria B
- Bulk current injection immunity: ISO 11452-4:201; criteria A
- Pulse 1, Pulse 2a, Pulse 2b, Pulse 3a, Pulse 3b, Pulse 4, Pulse 5a: ISO 7637-2:2011; criteria A



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#### **ELECTRICAL SPECIFICATIONS**

- Technology: Redundant Hall effect sensor
- Supply voltage range: 6 35 VDC
- Typical current consumption: 12 V @ 53 mA
- Transient overvoltage max: 40 V
- Reverse polarity Max: -1000 VDC
- Output signal: SAE CANbus J1939-71
- Connections: Deutsch DTM04-6p



#### **ELECTRICAL CONNECTIONS**

- Six position connector: Deutsch DTM04-6P
- Wire: 22 AWG, PTFE insulation with expandable sleeve
- Length: 6:00" +/- 0.5" (bottom of joystick to connector)



#### MECHANICAL SPECIFICATIONS

- Operation: Two axis
- Deflection angle: ±20° in X and Y directions
- Operating torque, breakout: .68 Nm \*
- Operating torque, 50% travel: .8 Nm \*
- Operating torque, 100% travel: 1.5 Nm \*
- Maximum axial load: 400 lbf.
- Expected life: 10 million lifecycles (X and Y axis)
- Lever Action (centering): Spring return

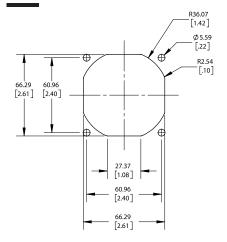


#### **MATERIALS**

- Shaft: Stainless steel
- Boot: Silicone
- Handles: Glass filled nylon
- Bezel: Hard black anodized aluminum
- Body: Aluminum
- Cover: Zinc plated steel
- Weight: 800 g



#### PANEL CUT-OUT





#### CAN J1939 INTERFACE SPECIFICATION

The XD Series utilizes redundant Hall effect sensors to measure the primary X and Y axis. The CAN controller support various button configurations as well as proportional thumbwheels and mini-joysticks for additional axis data.

All axis and button data are delivered on a CAN 2.0B compliant physical interface. Two additional signals allow configuration of the controller Source Address. Controller messages are delivered per the SAE J1939-71 message protocol.

CAN 2.0B INTERFACE PARAMETERS

- Baud rate: 250 Kbps
- Transmission repetition rate: 50 ms to 80 ms \*\*
- BJMI/EJMI interval time: 20 ms
- Terminating resistor: No (available by special request to factory)
- Connection to Deutsch DTM04-6P connector:

Pin	Color	Function
1	White	CAN Lo
2	Green	CAN Hi
3	Blue	Source Address SEL 1
4	Orange	Source Address SEL 0
5	Black	Ground
6	Red	6 - 35 VDC

<sup>\*\*</sup> Transmission repetition rate is dependent upon the faceplate configuration.

<sup>\*</sup> Operating force: configuration option «L»

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#### **CAN J1939 INTERFACE SPECIFICATION** (CONTINUED)

#### CAN MESSAGE PROTOCOL

- Primary Axis and button data on Basic Joystick Message 1 (BJM1):
  - Priority: 3
  - Base PGN: 0xFDD6
- Source address: 0x101
- Data field: 8 bytes
- Redundant Axis data on Extended Joystick Message 1 (EJMI):
- Priority: 3
- Base PGN: 0xFDD7
- Source address: 0x101
- Data field: 8 bytes
- Additional thumbwheels and mini-joysticks data on Extended Joystick Message 2 (EJM2):
- Priority: 3
- Base PGN: 0xFDD9 - Source address: 0x101 - Data field: 8 bytes

Note 1: Alternate source addresses can be configured by grounding of the blue and/or orange wires.

- Source address= Ox10: ORANGE= floating , BLUE= floating (default)
- Source address= Ox20: ORANGE= floating, BLUE= grounded Source address= Ox30: ORANGE= grounded, BLUE= floating
- Source address= Ox40: ORANGE= grounded, BLUE= grounded

#### BJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Primary X-axis neutral position status
1/3	2	Primary X-axis left position status
1/5	2	Primary X-axis right position status
1/7 to 2/8	10	Primary X-axis position data
3/1	2	Primary Y-axis neutral position status
3/3	2	Primary Y-axis down position status
3/5	2	Primary Y-axis up position status
3/7 to 4/8	10	Primary Y-axis position data
6/1	2	Button 4 status
6/3	2	Button 3 status
6/5	2	Button 2 status
6/7	2	Button 1 status
7/1	2	Button 8 status (Paddle if 6 button configuration)2
7/3	2	Button 7 status (Trigger if 6 button configurat ion)2
7/5	2	Button 6 status
7/7	2	Button 5 status
8/5	2	Button 10 status (Paddle if 8 button configuration)2
8/7	2	Button 9 status (Trigger if 8 button configuration)2

Note 2: If configured with n buttons, Trigger and/or paddle would be positioned in Button n+1 and Button n+2.

#### EJM1 DATA FIELD STRUCTURE:

START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	Redundant X-axis neutral position status
1/3	2	Redundant X-axis left position status
1/5	2	Redundant X-axis right position status
1/7 to 2/8	10	Redundant X-axis position data
3/1	2	Redundant Y-axis neutral position status
3/3	2	Redundant Y-axis down position status
3/5	2	Redundant Y-axis up position status
3/7 to 4/8	10	Redundant Y-axis position data

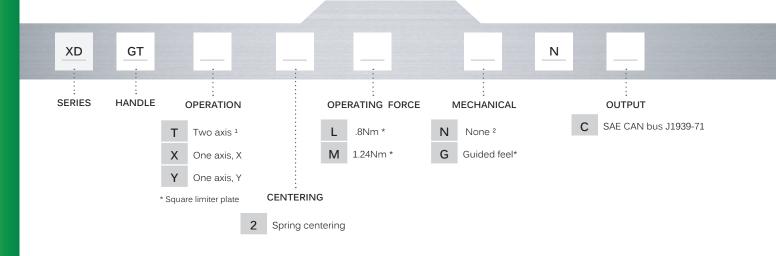
#### EJM2 DATA FIELD STRUCTURE:

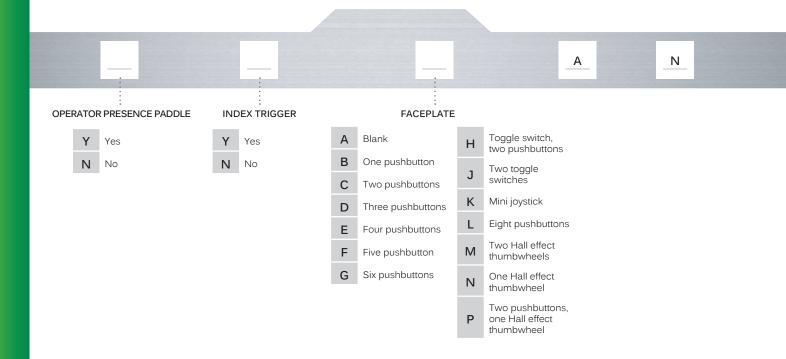
START POSITION (BYTE/BIT)	LENGTH (BITS)	FUNCTION
1/1	2	A-axis neutral position status
1/3	2	A-axis left position status
1/5	2	A-axis right position status
1/7 to 2/8	10	A-axis position data
3/1	2	B-axis neutral position status
3/3	2	B-axis left position status
3/5	2	B-axis right position status
3/7 to 4/8	10	B-axis position data
5/1	2	C-axis neutral position status
5/3	2	C-axis left position status
5/5	2	C-axis right position status
5/7 to 6/8	10	C-axis position data

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## **BUILD YOUR PART NUMBER**





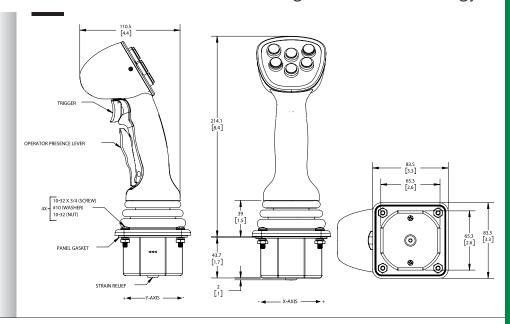
<sup>&</sup>lt;sup>1</sup> Measured at ±10° (50% travel) from center

<sup>&</sup>lt;sup>2</sup> The Guided feel option aids the joystick lever into the cardinal direction

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#### **DIMENSIONS**







## **COMPONENT DESCRIPTIONS**



- MT series: Sealed toggle switch
- MOM-OFF-MOM



- IM series: Sealed momentary pushbutton
- Snap action
- Red



- TS series : Miniature Hall effect joystick
- Two axis, proportional output
- Castle actuator



- One axis, proportional output
- Black wheel

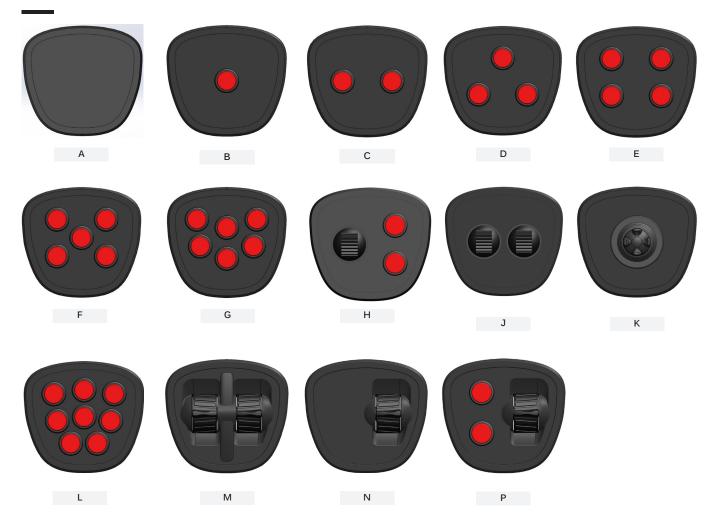




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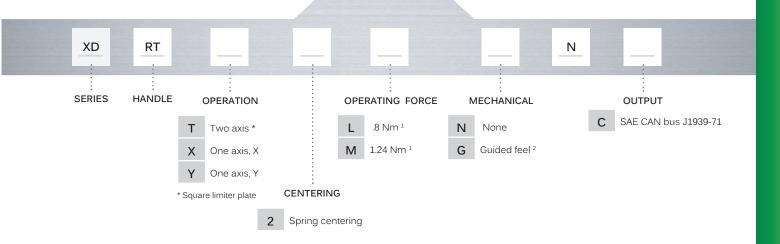
## **FACEPLATE OPTIONS**

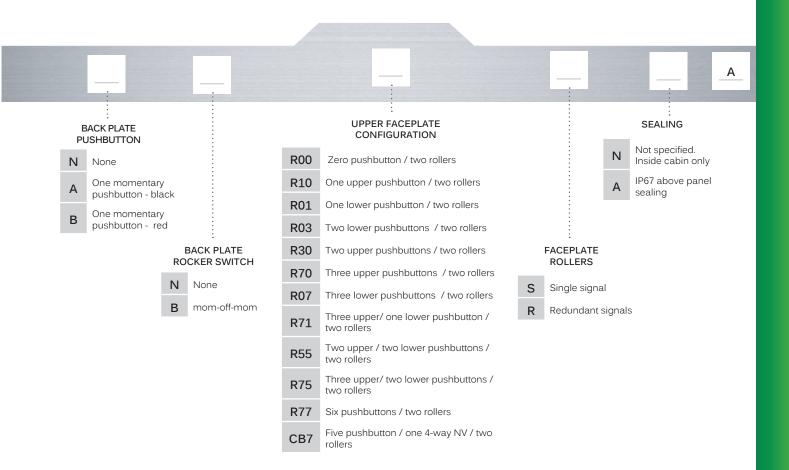


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# (E3)

#### **BUILD YOUR PART NUMBER**





<sup>&</sup>lt;sup>1</sup> Measured at ±10° (50% travel) from center

<sup>&</sup>lt;sup>2</sup> The Guided feel option aids the joystick lever into the cardinal direction

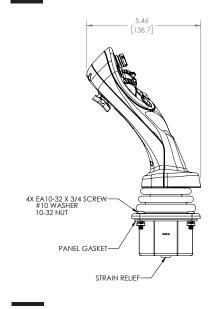
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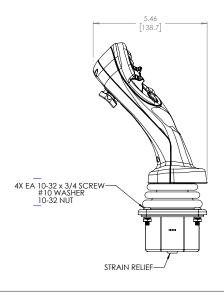
#### **CONTOURED FACEPLATE**

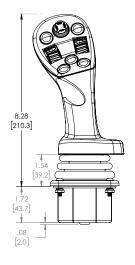


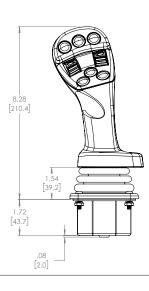
#### RAISED FACEPLATE













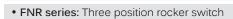
### **COMPONENT DESCRIPTIONS**



- IX series: Sealed momentary pushbutton
- Protective elastomer boot
- IP67 panel sealed
- Black



- Tactile feedback
- IP67 panel sealed



- Mom-off-mom actuation
- IP69K panel sealed



- NV series: 4 way navigation switch
- Tactical momentary actuation
- IP67 panel sealed



HR series: Hall effect thumbwheel

- One axis, proportional control
- Single or redundant outputs
- Optional IP67 panel sealing
- Black

# APEM

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## **BACK PLATE OPTIONS**



N no pushbutton N no rocker switch



N no pushbutton
B mom-off-mom rocker switch



A black pushbutton N no rocker switch



A black pushbutton
B mom-off-mom rocker switch



## RAISED FACEPLATE OPTIONS



R00



R10



R01



R03



R30



R70



R07



R71



R55



R75



R77

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## CONTOURED FACEPLATE OPTION



CB7